

RT302 Rotary Temperature Transmitter (850-321)

The RT302 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in a heated godet roll shell. The system consists of three components: The **RT302R** rotary assembly, the **RT300S** stationary assembly, and the **RT302C** controller interface assembly.



Installation

1. Install the flange adapter to the bearing block with the 1/4-20 x 5/8" mounting hardware provided. (Note: Flange adapter converts existing bearing block face to accept Binsfeld stationary assembly.) Pilot ring faces bearing block.
2. Slide the RT302R rotary assembly onto shaft with steel base toward motor. Tighten the (2) 1/4-20 compression screws (alternating from one screw to the other) to lock assembly onto shaft.

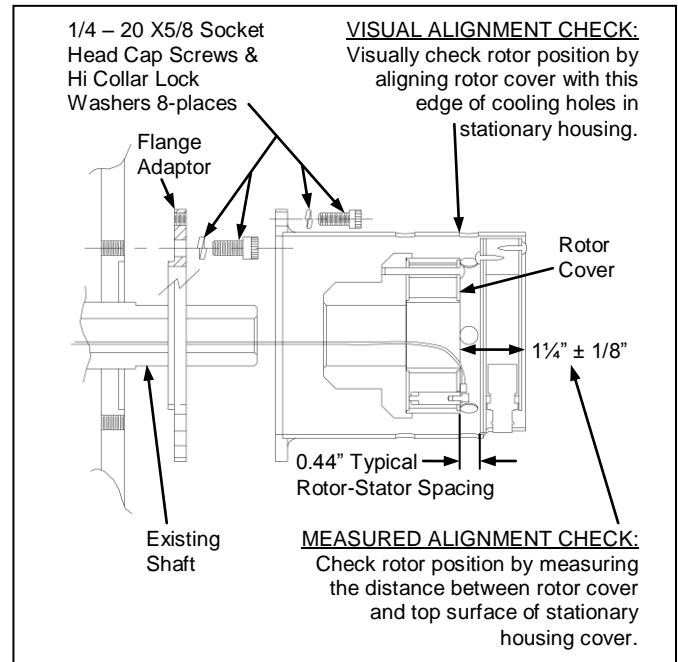
Note: The RT302R requires proper positioning on the shaft; see Step 6 below for details.

3. Secure RTD leads with the 4-40 x 1/4" socket head cap screws provided (see Rotor-RTD Wiring Diagram).
4. **IMPORTANT!** Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against inside cover of RT300S stationary housing during rotation.
5. Carefully position the RT300S stationary housing over shaft-mounted RT302R transmitter and mount it to the motor using (4) 1/4 - 20 x 5/8" long socket head cap screws and lock washers provided.
6. **IMPORTANT!** Refer to the Installation Diagram to verify correct axial spacing between rotor and stator using either of the following methods:

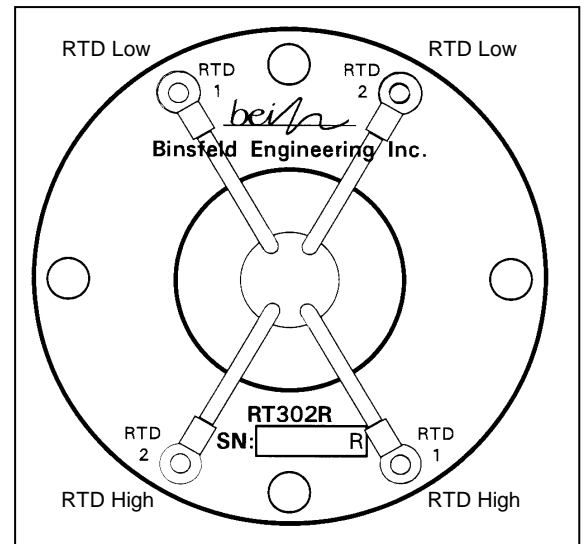
Visual Alignment: sight the outer face of the rotor through the side ventilation holes in the stator.

Measured Alignment: insert a steel scale through the ventilation slots in the cover of the stator and measure 1-1/4 ± 1/8 inches from the stator (RT300S) cover to the outer face of the rotor.

7. DIN rail (35mm) mount the RT302C current controller interface at a convenient location. **CAUTION:** To promote airflow and prevent overheating, the RT302C must have at least 1-inch clearance above and below the enclosure.
8. Connect TNC end of the provided coax cable to the TNC connector on the RT300S stationary housing and the BNC end to the BNC connector on the RT302C.
9. Connect a power source to the proper terminals indicated on the RT302C. Acceptable power is 22-35VDC or 17-27VAC. **CAUTION: Power source must be isolated from current output.**
10. Connect the 4-20mA current loop (from the customer's process controller) to the current source terminals indicated on the RT302C.
11. Allow 30 seconds for start up.



Installation Diagram



Rotor-RTD Wiring Diagram

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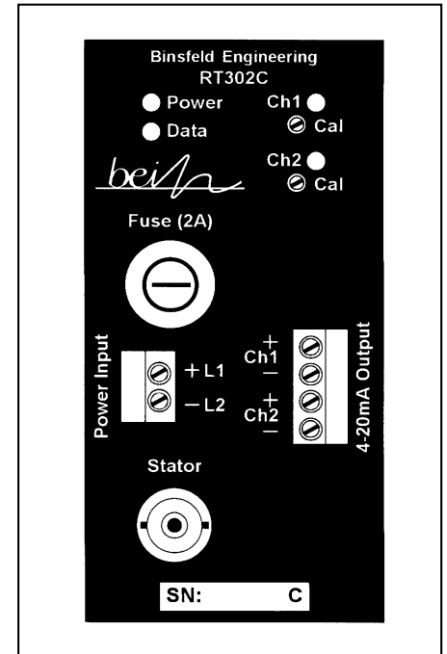
Troubleshooting

In normal operating mode the Power status light, the Data status light and the Channel (Ch) status light are all on solid. In error mode, one or more of the lights on the RT302C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

Power Status	Condition	Corrective Action
On solid	Stator & rotor power in spec	---
Flash fast (5Hz)	Rotary power out of spec	Check rotor/stator spacing, and coaxial connections
Flash slow (2Hz)	Stationary power out of spec	Check power source
Off	System not powered	Check power source, and power connections
10 sec on/1 sec off [Data light off, RTD light(s) blinking]	Insufficient rotary power or data not received (Rotor Reset mode)	Check rotor/stator spacing, and coaxial connections

Data Status	Condition	Corrective Action
On solid	Digital transmission is error-free	---
Flickering	Intermittent transmission errors	Check rotor/stator spacing, and coaxial connections
Off	Data not received	Check rotor/stator spacing, and coaxial connections

Ch 1 - 2 Status	Condition	Corrective Action
On solid	No errors detected	---
Flash fast (5Hz)	Rotary side error: RTD out of range (including open or shorted)	Check RTD, connections
Flash slow (2Hz)	Open circuit in 4-20mA loop continuity of current loop	Check connections and



Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT302C for 5 seconds, and then restore power (to reset the digital circuitry). Go to <http://www.binsfeld.com/temptrak/rt300/> for more trouble shooting aids.

Specifications

Rotor:	Number of sensors:	1 - 2
	Sensor connection:	#4-40 screw terminals with socket-head cap screws
	Input sensor type:	PT100 RTD (100 Ω at 0°C, $\alpha = .00385$, two wire)
	Sensor range:	0 – 300° C
	Speed:	10,000 RPM
Stator:	Connector:	Coaxial interconnect (TNC)
Controller Interface:	Output connection:	Quick connect screw terminal block.
	Output signal:	4-20 mA (Linear with 0° to 300° C)
	Power input:	22-35 VDC or 17-27 VAC, 2 A max, .5 A nominal
	Max load resistance	400 Ω
General:	Accuracy (typical error):	$\pm 0.30\%$ span over operating temperature range
	Operating temperature:	0 – 100° C
	Humidity:	0 – 90% RH, non-condensing

This document is subject to change without prior notification.

Warranty

Binsfeld Engineering Inc. warrants this product to be free from defective materials and workmanship for a period of five years from the date of delivery to the original purchaser and that this product will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.