RT304 Rotary Temperature Transmitter (850-363)

The RT304 rotary temperature transmitter is a digital system designed to accurately transmit temperature data from RTD sensors embedded in a heated godet roll shell. The system consists of three components: The RT304R rotary assembly, the RT300S stationary assembly, and the RT304C controller interface assembly.



Installation

- Secure the RT304R rotating transmitter module (provided) to rotating base using M4 button head cap screws with thread-locking adhesive Loctite 222MS (provided). Use 4 screws per module. Apply thread-locking adhesive sparingly to the last few threads at the end of each screw.
- Attach the RT300S stationary subassembly (provided) to stationary housing using Phillips pan head self-tapping screws. Use 4 screws per assembly. Align the BNC connector with the cut-away at the top of the housing. The decorated and serialized side should face up. See Stationary Assembly Diagram.
- Slide the RT304R rotary assembly onto shaft with steel base toward motor until base hits step on shaft. Tighten the (2) M6 compression screws (alternating from one screw to the other) to lock assembly onto shaft.

Note: Proper positioning required, see Step 7.

- Review the drawing below for wiring the RTD connections onto the RT304R rotary assembly. Secure leads with the M3 socket head cap screws provided.
- IMPORTANT! Pull excess RTD leads towards the front of the godet roll to be stored under the godet cover. This prevents lead wires from rubbing against inside cover of RT300S stationary housing during rotation.
- 6. Carefully position the RT300S stationary housing over shaft-mounted RT304R transmitter and mount it using (4) M8-1.25 x 20mm long socket head cap screws and lock washers provided.
- 7. **IMPORTANT!** Refer to the Installation Diagram to verify correct axial spacing between rotor and stator using either of the following methods:

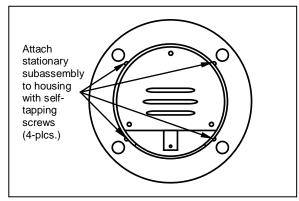
<u>Visual Alignment</u>: sight the outer face of the rotor through the side ventilation holes in the stator.

<u>Measured Alignment</u>: insert a steel scale through the ventilation slots in the cover of the stator and measure $1-1/4 \pm 1/8$ inches from the stator (RT300S) cover to the outer face of the rotor.

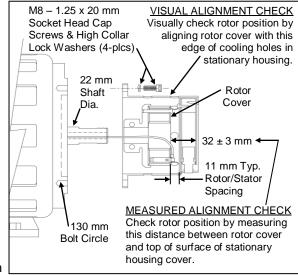
- Remove and discard the existing connector from the coaxial cable at the motor and replace it with the BNC cable crimp plug provided. Connect BNC plug to BNC connector on the RT300S stationary assembly.
- DIN rail (35mm) mount the RT304C current controller interface at a convenient location. CAUTION: To promote airflow and prevent overheating, the RT304C must have at least 1-inch clearance above and below the enclosure.
- 10. Connect a power source to the proper terminals indicated on the RT304C. Acceptable power is 22-35VDC or 17-27VAC.

CAUTION: Power source must be isolated from current output.

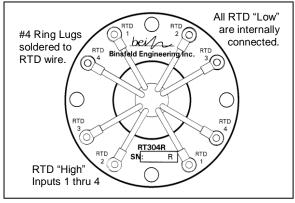
- 11. Connect the 4-20mA current loop (from the customer's process controller) to the current source terminals indicated on the RT304C.
- 12. Allow 30 seconds for start up.



Stationary Assembly Diagram



Installation Diagram



Rotor/RTD Connections

RT304 Rotary Temperature Transmitter (850-363)

mode)

Troubleshooting

In normal operating mode the Power status light, the Data status light and the CH status light are all on solid. In error mode, one or more of the LED's on the RT303C Controller Interface will flash and a high temperature signal (approximately 24 mA) will be output. Refer to the table below when troubleshooting an error mode event.

	, ·
Power Status	Condition
On solid	Stator and rotary power in spec
Flash fast (5Hz)	Rotary power out of spec
Flash slow (2Hz) Off	Stationary power out of spec System not powered
10 sec on/1 sec off [Data light off, RTD	Insufficient rotary power or data not received (Rotor Reset mode)

light(s) blinking)

Data Status Condition Digital transmission is error-free On solid Flickering Intermittent transmission errors

Off Data not received

Ch 1 Status Condition No errors detected On solid Flash fast (5Hz) Rotary side error:

RTD out of range (including

open or shorted)

Open circuit in 4-20mA loop Flash slow (2Hz)

Corrective Action

Check rotor/stator spacing, and coaxial connections Check power source Check power source, and

power connections

Check rotor/stator spacing, and coaxial connections

Corrective Action

Check rotor/stator spacing,

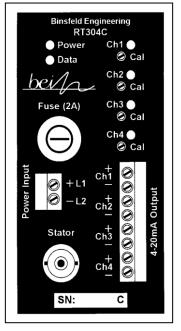
coax connections

Check rotor/stator spacing, and coaxial connections

Corrective Action

Check RTD, connections

Check connections and continuity of current loop



Status Indicators & I/O Diagram

If the status lights do not agree with conditions listed above, remove power to the RT304C for 5 seconds, and then restore power (to reset the digital circuitry). Go to http://www.binsfeld.com/temptrak/rt300/ for more trouble shooting aids.

Specifications

Rotor: Number of sensors

> Sensor connection: M3-0.5 screw terminals with socket-head cap screws Input sensor type: PT100 RTD (100 Ω at 0° C, α =.00385, two wire)

0 - 300° C Sensor range: Speed: 10,000 RPM

Stator: Connector: Coaxial interconnect (BNC)

Controller Output connection: Quick connect screw terminal block. Interface: Output signal: 4-20 mA (Linear with 0 - 300° C)

> Power input: 22-35 VDC or 17-27 VAC; 2A max, 0.5A nominal

Max load resistance 400 Ω

General: Accuracy (typical error): ±0.30% span over operating temperature range

Operating temperature: 0 - 100°

Humidity: 0-90% RH. non-condensing

This document is subject to change without prior notification.

Warranty

Binsfeld Engineering Inc. warrants this product to be free from defective materials and workmanship for a period of five years from the date of delivery to the original purchaser and that this product will conform to specifications and standards published by Binsfeld Engineering Inc. Upon evaluation by Binsfeld Engineering Inc., any product found to be defective will be replaced or repaired at the sole discretion of Binsfeld Engineering Inc. Our warranty is limited to the foregoing. Binsfeld Engineering Inc. disclaims any warranty of merchantability or fitness for intended purpose.